

Representational Momentum Transcends Motion

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August 27, 2025

Abstract

To navigate the world, our minds must represent not only how things are now (perception), but how they are about to be (prediction). However, perception and prediction blur together for objects in motion, a classic finding known as “representational momentum”. If you glance at a photo of a person diving into a lake, you will tend to remember them closer to the water than they really were. In seven experiments, we show that this phenomenon transcends motion: Our minds make predictions that distort our memories about changes that involve no motion whatsoever, including changes in brightness, color saturation, and proportion. Additionally, we use representational momentum to map the limits of automatic prediction, showing that there are no analogous effects for changes in hue. Our automatic predictions distort our memories in many domains—not just motion—and the presence or absence of these distortions expose the inner workings of perception, cognition, and memory.

Research Transparency Statement

All experiment scripts, data, and analysis scripts are available on OSF: <https://osf.io/j9d4a/>. Demos of all experiments are available here: <https://subjectivitylab.org/rm/>. All of our experiments were preregistered. Links to all preregistrations are in the OSF repository README.

Introduction

Things change. Dawn brightens. Predators approach. Alliances fray. To navigate the world, our minds must represent not only how things are now, but how they are about to be. Even just to perceive the world, our minds rely on prediction. It is easier to hit a baseball if you anticipate where it is about to be (Poulton, 1957), but it is also easier to see a baseball if you anticipate seeing one (Bar, 2004; De Lange et al., 2018; von Helmholtz, 1924).

29 A striking consequence of this constant prediction is *representational momentum*: Our
30 memories of moving things tend to reflect not just what we saw, but what we were anticipating
31 (Freyd, 1983; Freyd and Finke, 1984; Hubbard, 2005, 2014). Watch a shape rotate and you will
32 tend to remember it as having rotated a few extra degrees (Freyd and Finke, 1984). Watch it
33 move left-to-right and you will tend to remember its final position too far to the right (Hubbard
34 and Bharucha, 1988). This occurs even with still images of things in motion. Glance at a photo
35 of a person jumping off a ledge and you will tend to remember seeing them closer to the ground
36 (Freyd, 1983).

37 Is representational momentum a motion-specific phenomenon? Or do we make automatic
38 predictions that distort our memories for other components of our experience, revealing something
39 more general about the relationship between prediction, perception, and memory? On one
40 hypothesis, our minds represent and forecast the trajectory of *any* predictable, continuous change
41 that we perceive, resulting in representational momentum in many domains, not just for motion
42 through space (e.g., Freyd, 1993; Freyd et al., 1990). On an opposing hypothesis, we experience
43 representational momentum only for motion that we observe or infer (e.g., Brehaut and Tipper,
44 1996).

45 Two findings suggest that representational momentum may be more than just a quirk of
46 motion perception. First, people experience representational momentum for changes in auditory
47 pitch (Kelly and Freyd, 1987). Second, people have been shown to experience representational
48 momentum for “state changes” (e.g., an ice cube melting into a puddle; Hafri et al., 2022).
49 However, the state changes that are known to induce representational momentum still involve
50 motion (e.g., a shrinking ice cube and expanding puddle), and rising and falling pitches sound like
51 objects in motion (it has been argued; Brehaut and Tipper, 1996), leaving open the possibility
52 that these are just more cases of representational momentum for observed or inferred motion.
53 Additionally, and most notably, experiments have failed to find representational momentum for
54 changes in brightness (Brehaut and Tipper, 1996; Favretto, 2002, as cited in Hubbard, 2015),
55 further casting doubt on the generality of representational momentum beyond motion.

56 Here, we demonstrate unambiguously that representational momentum transcends motion:

57 Our minds make predictions that distort our memories about changes that involve no motion
58 whatsoever. In our first four experiments, we show that—contrary to the established view
59 (Brehaut and Tipper, 1996; Hubbard, 2015)—people *do* experience representational momentum
60 for changes in the brightness of completely motionless stimuli. Participants misremember
61 brightening stimuli as brighter than they really were and darkening stimuli as darker than they
62 really were. In our fifth and sixth experiments, we show the same for two more dimensions of
63 change entirely unrelated to motion: changes in color saturation and changes in proportions.
64 Participants remember saturating stimuli as more saturated, desaturating stimuli as less saturated,
65 and things that were increasing in prevalence as being even more prevalent than they were. In our
66 final experiment, we investigate the limits of automatic prediction. In particular, we hypothesize
67 that the mind does not automatically represent the trajectory of changes in hue. Even though
68 there is latent organization to hue representation, we suspect that our minds do not naturally
69 compute or explicitly represent the *trajectory* of changes within this latent space and, therefore,
70 do not make automatic predictions about changing hue. Consistent with this hypothesis, we find
71 that our participants do not experience representational momentum for changing hue.

72 **Experiment 1: Representational Momentum for Brightness**

73 Do our minds make automatic predictions that distort our memories for anything other than
74 motion (i.e., the positions of things that are moving through space)? Experiment 1 performed
75 a basic test for representational momentum for changing brightness: We showed people a
76 brightening or darkening animation and asked them to indicate how the animation ended,
77 then checked if they overestimated how bright the brightening animations had become and
78 overestimated how dark the darkening animations had become.

79 This approach differs from prior experiments that failed to find representational momentum
80 for brightness (Brehaut and Tipper, 1996), which adapted the earliest methods used to study
81 representational momentum for motion. Those experiments used impoverished stimuli (e.g.,
82 staccato three-frame animations), whereas our experiments used longer, smoother stimuli that

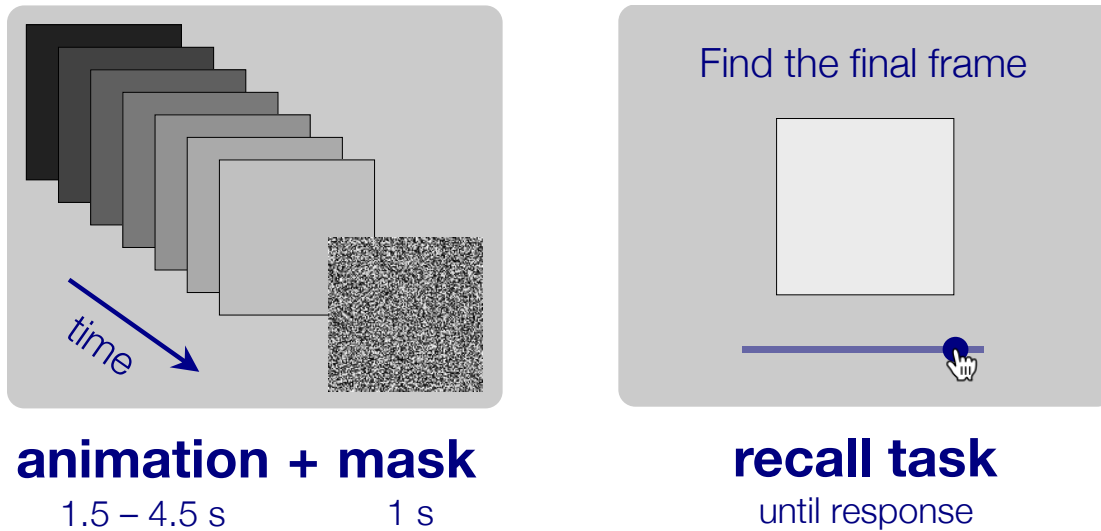


Figure 1: Procedure used in Experiment 1 and adapted for all other experiments. Participants watched an animation of a square that became either brighter or darker. A mask abruptly cut off the animation at a random point on each trial. After the mask, participants used a slider to move frame-by-frame through the full animation to try to select the last frame displayed before the mask.

83 provided a much stronger signal of the trajectory of change to serve as a basis for prediction.

84 Method

85 On each trial of Experiment 1, participants watched an animation of a gray square that gradually
 86 became either brighter or darker (see Figure 1). At a random point during the animation, the
 87 square was abruptly hidden by a mask. Participants then tried to identify the last frame that they
 88 saw before the mask appeared by using a slider to move frame-by-frame through the animation
 89 (adapting the methods of Hafri et al., 2022).

90 If people experience representational momentum for changing brightness, participants' re-
 91 sponses would be biased toward later frames: They would recall the last frame of a brightening
 92 animation as brighter than what was actually shown and the last frame of a darkening animation
 93 as darker than what was actually shown.

94 Implementation Details

95 The animation consisted of 180 frames equally spaced in CIELCh space between lightness values
96 of 5 and 95, displayed at 30 frames per second. Brightening animations always started at lightness
97 5 (almost black), darkening animations at lightness 95 (almost white). Chroma and hue angle
98 values were fixed at 0. The square was 240 by 240 pixels with a 1 pixel black border. The entire
99 experiment was presented on a middle gray background (RGB: #777777; CIELCh lightness
100 50.03).

101 The final frame displayed before the mask varied randomly from frame number 23 to frame
102 number 157, with all points within that range equally likely. Accordingly, the mask could appear
103 anywhere from 0.77 to 5.23 seconds into the animation. The mask was one of seven different
104 grayscale noise images, selected at random on each trial.¹ This mask was displayed for 1 second
105 before the slider appeared. The draggable button on the slider started at a random location
106 on each trial, but no frame from the animation was displayed until the participant clicked or
107 dragged the button to a new location. The far left of the slider corresponded to the first frame
108 of the animation (i.e., the darkest square for a brightening animation and the brightest for a
109 darkening animation) and the far right corresponded to the 180th frame. Participants could
110 move freely back-and-forth through the frames of the whole animation for as long as they wanted
111 on each trial. When satisfied with their chosen frame, participants clicked a button to submit
112 their response and proceed to the next trial.

113 Each participant completed 4 practice trials, followed by 30 analyzed trials. Except for
114 the first practice trial, participants received no feedback. For each participant, the direction
115 of the animation (brightening vs. darkening) was the same on every trial. Participants were
116 randomly assigned to the brightening or darkening condition. This was the only between-subjects

¹The average brightness of pixels in the mask images was 50%. This ensures that, even if participants confuse or combine the mask and the final frame of the animation in their memories, this alone would not produce momentum-like effects. A bias toward the brightness of the mask would just be a bias toward 50% brightness. This would look like momentum when the final frame of the animation was below 50% brightness, but it would look like the opposite of momentum when it was above 50% brightness, and these effects would cancel out because these cases were equally likely. This was true (for the relevant dimension) for all experiments except Experiment 6. In Experiment 6, the animation was more likely to end after the midpoint, meaning that a bias toward the mask could only make it harder to detect momentum effects.

manipulation. Demos of all experiments are available here: <https://subjectivityresearch.org/rm/>

Participants

In all seven experiments, the participants were adults in the United States recruited through the online platform Prolific.² Participants who completed any of the experiments were prevented from enrolling in any of the subsequent experiments.

220 participants completed Experiment 1 (126 male, 88 female, 4 non-binary, 2 declined to specify; mean age 39). Our final analyses included 124 participants who saw a brightening stimulus and 91 who saw a darkening stimulus. The remaining 5 participants were excluded by our preregistered exclusion criteria (see Statistical Analyses).

Statistical Analyses

Our measure of interest was the error in each participant's response on each trial: the difference between the frame number of the last frame that they remembered seeing and the frame number of the last frame that was actually presented. If the last frame they remembered seeing was before the final frame, this would be a negative error. By contrast, if the last frame that they remembered seeing was an upcoming frame that never appeared on that trial, this was a positive error. If people experience representational momentum for changes in brightness, this would shift their errors in the positive direction.

Adhering to our preregistered analysis plan, we excluded participants from our analyses if the absolute value of their error was more than 2.5 standard deviations larger than the mean of all participants' mean absolute error.

We modeled participants' errors with a simple Bayesian multilevel model using brms and Stan (Bürkner, 2017; Carpenter et al., 2017). We modeled participants' errors as a linear function of

²Because our experiments were run online, we could not control conditions such as the ambient lighting or the configuration of participants' displays. However, any variation in testing conditions that occurred merely demonstrates the robustness of our findings. No variability in ambient lighting or in the calibration of participants' displays, for example, could produce false positives because none of our demonstrations of representational momentum depend on between-subjects comparisons, specific ambient light levels, specific monitor brightness settings, or well-calibrated displays (in this or any of our experiments). Participants only need to be using the same display during their responses as during the stimulus presentations (1 second earlier), which is an extremely safe assumption.

139 the direction of the animation they saw (brightening or darkening) plus Gaussian noise, while
140 allowing random intercepts for each participant, and using Gaussian distributions centered on
141 0 and bounded at (-90, 90) with standard deviation 15 as the priors for the intercept and the
142 effect of direction. The standard deviation of the priors were selected based on our pilot data
143 and the size of other representational momentum effects observed in the literature (e.g., Hafri
144 et al., 2022). These values were preregistered, but also make very little difference because the
145 influence of the priors is overwhelmed by the amount of data that we have.

146 We used effect coding for the direction variable so that the intercept coefficient could be
147 interpreted as the overall error and calculated a 95% posterior highest density interval (HDI)
148 for the intercept coefficient. Our preregistered prediction was positive overall error (i.e., a 95%
149 posterior HDI entirely above 0). We also computed 95% HDIs for the effect in each of the two
150 direction conditions.

151 We do not calculate or report Bayes factors as part of any of our experiments. Using Bayes
152 factors to compare null and alternative hypotheses gives disproportionate influence over the
153 outcome of the analyses to the particular prior distributions that are chosen (Kruschke, 2014;
154 Liu and Aitkin, 2008). Instead, we simply estimate and interpret the relevant parameters of
155 the model, namely 95% HDIs for participants' errors under different conditions. The meaning
156 of these HDIs is intuitive: Given our priors (i.e., that any effect is likely to be small and is as
157 likely to be negative as positive), there is a 95% probability that the magnitude of the effect falls
158 within the 95% HDI. And, unlike with Bayes factors, the priors do not actually matter much.
159 With the amount of data that we have in our experiments, any reasonable priors will yield nearly
160 identical results.

161 For all experiments, additional details about the procedural and analytical methods are
162 provided in the Supplementary Materials.

163 Results

164 Participants exhibited representational momentum for changing brightness: When the animation
165 was growing brighter, they tended to remember the final frame as brighter than it really was, but

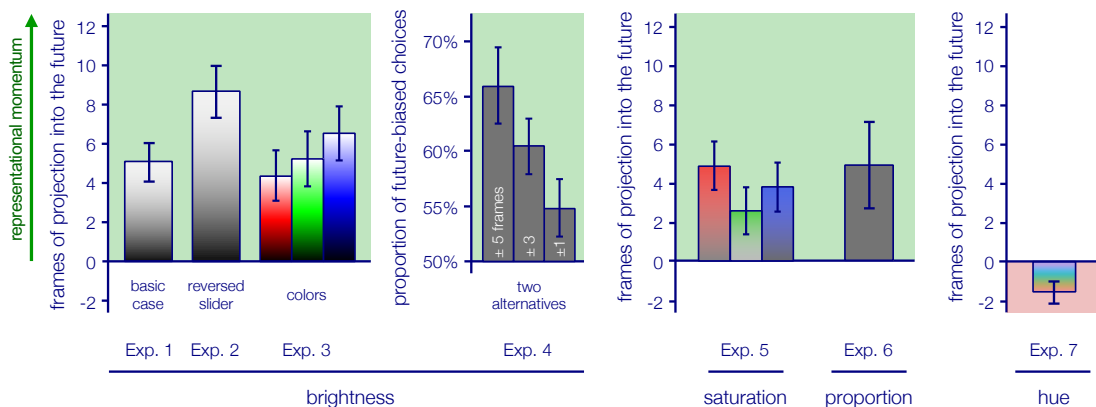


Figure 2: Participants consistently experienced representational momentum for changing brightness (Exps. 1-4). When tasked with choosing the final frame in an animation that was cut short, they tended to choose upcoming frames that had not yet been displayed (brighter squares for brightening squares and darker squares for darkening ones). This did not reflect a simple bias to respond to the right of the slider (Exp. 2), held for different colors (Exp. 3), and held when participants were only given two (equally incorrect) frames to choose between (Exp. 4). Participants also experienced representational momentum for changes in color saturation (Exp. 5) and for changes in proportion (Exp. 6), two additional varieties of change unrelated to motion. Participants did not experience representational momentum for changes in hue (Exp. 7), which serves as a power control for the other experiments, in addition to locating a limit of automatic prediction. Bar values are medians of the relevant posterior probability distributions. Error bars correspond to posterior 95% highest density intervals (HDIs).

166 when it was growing darker, they tended to remember the final frame as darker (see Figure 2).
 167 On average, the final frame of the animation that participants remembered seeing was a frame
 168 that had not appeared yet and would not have been displayed until 5.54 frames (~ 183 ms) after
 169 the mask appeared (posterior 95% highest density interval [HDI] for the model intercept: [4.09,
 170 6.02]). Importantly, this effect held for both brightening and darkening stimuli—with 95% HDIs
 171 of [6.94, 9.47] and [0.55, 3.48], respectively—which confirms that it is not driven by a simple bias
 172 to remember everything as brighter (or everything as darker) than it really was.³

³For standardized versions of these effect size estimates, see the Supplementary Materials.

173 Experiments 2–4: Replications with Different Tasks and Stimuli

174 Experiments 2 through 4 verified that people consistently exhibit representational momentum
175 for changes in brightness across variations in the stimuli and tasks used to elicit it.

176 In Experiment 1, participants chose the last frame that they remembered seeing by using a
177 slider that moved frame-by-frame through the animation as the slider was moved from left to
178 right. Accordingly, what looked like representational momentum (i.e., a bias to choose a later
179 frame) could have been merely a bias to respond toward the right of the slider. Experiment 2
180 directly replicated Experiment 1 while also ruling out this possibility by reversing the direction
181 of the slider.

182 Experiment 3 replicated Experiment 1 using red, green, and blue stimuli, rather than
183 achromatic stimuli. Although brightness and hue are classically considered to be independent
184 features of visual stimuli (e.g., Krantz, 1972), changes in one can impact the representation and
185 perception of the other (e.g., Burns and Shepp, 1988). Accordingly, it is conceivable that the mind
186 could make automatic predictions only about changes in the brightness of achromatic stimuli,
187 or only for certain hues. Experiment 3 demonstrated that people experience representational
188 momentum for changes in brightness along a variety of different trajectories through color space,
189 and not just for achromatic stimuli.

190 Experiment 4 showed that people experience representational momentum for changes in
191 brightness using a different measure, eschewing the slider-based response entirely for a two-
192 alternative choice task.

193 Method

194 Experiment 2 exactly replicated Experiment 1 except that the response slider ran in reverse: the
195 far left of the slider corresponded to the last frame of the animation (e.g., the darkest frame for
196 a brightening animation) and the far right of the slider corresponded to the first frame of the
197 animation. Our statistical analyses were identical to those used for Experiment 1.

198 Experiment 3 exactly replicated Experiment 1, except that the brightening or darkening

199 square on each trial was red, green, or blue, rather than gray (determined randomly on each trial,
200 with all three options equally likely). Each animation consisted of 180 frames equally spaced in
201 HSL space between lightness values of 0 and 1. All three stimuli had a fixed saturation value of
202 1. The red, green, and blue stimuli had fixed hue angles of 0, 120, and 240 degrees, respectively.
203 The random noise mask on each trial was matched to the hue of the stimulus on that trial. Our
204 methods for analyzing the data in Experiment 3 were identical to those for Experiments 1 and 2,
205 except we also included stimulus color as a predictor (using effect coding so that the intercept
206 coefficient could still be interpreted as the overall error, and including random slopes for the
207 effect of color, as it was a within-subjects manipulation).

208 Experiment 4 replicated Experiment 1 except that i) participants were only provided two
209 options when asked to report the final frame that they remembered seeing, and ii) there were
210 60 trials instead of 30. After the brightening or darkening animation was masked, participants
211 were presented with two side-by-side squares (both also 240 x 240 pixels). Unbeknownst to the
212 participants, one option was always slightly lighter than the final frame before the mask and
213 the other was always slightly darker than the final frame before the mask. Participants were
214 asked to choose the option that best matched their memory of the final frame before the mask.
215 Participants responded using their keyboard, pressing the left or right arrow to indicate their
216 choice. The two options were always an equal number of frames off from the final frame that
217 was displayed, with the number of frames varying randomly between 1, 3, and 5 frames from
218 trial to trial (each option equally likely). The position of the two options (brighter on the left vs.
219 darker on the left) varied randomly from trial to trial (with each option equally likely).

220 In Experiment 4, our measure of interest was the probability that participants chose the
221 upcoming, unseen frame from among the two alternatives. In other words, when a participant
222 was asked to choose the best match for their memory of the final frame of a brightening square,
223 what was the probability that they would choose the option that was too bright (rather than
224 too dark)? And vice versa for a darkening frame. We used a simple Bayesian multilevel model
225 for this probability, analogous to the models used in Experiments 1–3, adding the offset of the
226 two options (1, 3, or 5 frames from correct) as a predictor (see the Supplementary Materials for

227 details). Adhering to our preregistered analysis plan, we excluded all trials with response times
228 faster than 200 ms or slower than 6000 ms. We also excluded all trials from participants who
229 responded outside of this range on 10% or more of the trials.

230 110 participants completed Experiment 2 (61 male, 47 female, 2 non-binary; mean age 36): 2
231 who were excluded by our preregistered exclusion criteria, 64 who saw a brightening stimulus
232 and 44 who saw a darkening stimulus. 100 participants completed Experiment 3 (49 male, 50
233 female, 1 non-binary; mean age 38): 2 who were excluded, 44 who saw a brightening stimulus,
234 and 54 who saw a darkening stimulus. 110 participants completed Experiment 4 (44 male, 63
235 female, 3 non-binary; mean age 38): 11 excluded, 58 who saw a brightening stimulus, and 41
236 who saw a darkening stimulus.

237 Results

238 Experiments 2–4 all found that participants exhibited representational momentum for changes
239 in brightness.

240 Experiment 2 replicated the results of Experiment 1: Participants’ memories for the final
241 frame of a brightening animation were projected an average of 11.0 frames into the future and
242 their memories of a darkening animation were projected an average of 6.3 frames into the future
243 (95% HDIs: [9.29, 12.72] and [4.22, 8.45], respectively). Thus, if anything, the momentum effect
244 was stronger when left-to-right movement on the response slider moved backward through time
245 instead of forward. The effects seen in Experiment 1 cannot simply be attributed to a bias to
246 respond to the right of the slider.

247 Experiment 3 found representational momentum for chromatic stimuli in all cases that we
248 tested, with 95% HDIs of [3.11, 5.65], [3.92, 6.69], and [5.10, 7.85] for red, green, and blue,
249 respectively (collapsing brightening and darkening conditions), verifying that it is not specific to
250 the achromatic stimuli.

251 Experiment 4 also found the signature of representational momentum in the two-alternative
252 choice task: Participants who saw the stimulus getting brighter chose the too-bright option 63.1%
253 of the time while those who saw it getting darker instead chose the too-dark option 56.1% of the

time (95% HDIs: [59.8%, 65.9%] and [54.1%, 61.6%], respectively; [57.9%, 62.9%] overall⁴). This held regardless of whether the two options were 5, 3, or even just 1 frame removed from the true final frame (95% HDIs: [62.5%, 69.3%], [57.9%, 62.9%], [52.2%, 57.4%], respectively).

Experiment 5: Representational Momentum for Saturation

Experiments 1–4 demonstrated that people experience representational momentum for increasing or decreasing brightness, a dimension of change that involves no motion whatsoever. Experiment 5 demonstrated that representational momentum extends to a second case of this kind: changes in color saturation. Like brightness, saturation is a rare example of a perceptual feature that can undergo continuous change without associated motion, providing the opportunity for a second, independent demonstration that representational momentum is not merely a quirk of motion perception, but a more general phenomenon.

Method

Experiment 5 followed the procedure of Experiment 1 except that the stimuli were red, green, or blue squares that increased or decreased in color saturation, rather than brightness, and the animations changed at 15 frames per second instead of 30 frames per second. The animations consisted of 90 frames equally spaced in CIELCh space between chroma values of 0 and 75. The red stimulus had fixed lightness of 55 and hue angle of 30. The green stimulus had fixed lightness of 75 and hue angle of 135. The blue stimulus had a fixed lightness of 45 and hue angle of 290.⁵ These values (and the change to 15 fps from 30 fps) ensured that every frame of each animation used a distinct RGB value that could be displayed on a standard display (i.e., no two frames were the same and the value of each RGB color channels was always between 0 and 255). Stimulus

⁴Converted to probabilities from the log-odds used in our preregistered analyses for simplicity.

⁵Even the CIELCh color space does not have perfectly independent and perceptually uniform dimensions (due to the Helmholtz–Kohlrausch effect and individual differences in color perception; Fairchild and Pirrotta, 1991; Judd, 1958; Kohlrausch, 1935), so our participants may have perceived slight changes in the brightness of the stimuli even with the CIELCh lightness fixed. However, any such changes would have been miniscule (and irregular) compared to the dramatic changes in brightness in Experiments 1–4. We exclude the highest saturation values of each color to minimize this effect.

275 hue varied randomly from trial to trial with each of the three hues equally likely.

276 100 participants completed Experiment 5 (45 male, 53 female, 2 non-binary; mean age 37): 4
277 participants excluded according to our preregistered exclusion criteria, 53 participants who saw
278 saturating stimuli, and 43 participants who saw desaturating stimuli.

279 Our statistical analyses were identical to those used for Experiment 1 except that we included
280 stimulus color as a predictor.

281 Results

282 Participants experienced representational momentum for both increasing and decreasing satu-
283 ration (95% HDIs of [3.49, 6.18] and [1.01, 4.04], respectively, [2.73, 4.72] overall), and for all
284 three stimulus colors (95% HDIs: [3.61, 6.07] for red, [1.38, 3.77] for green, [2.54, 5.04] for blue).
285 Participants who watched the stimulus become more saturated remembered it being even more
286 saturated than it really was in the final frame of the animation. Participants who watched it
287 become less saturated exhibited the opposite effect.

288 Experiment 6: Representational Momentum for Proportion

289 Experiment 6 demonstrated that representational momentum extends to yet another variety of
290 change that involves no motion whatsoever: change in the proportion of items in a set that are
291 one type versus another. We showed participants an animation of a two-color array of pixels
292 (e.g., every pixel was either yellow or blue) in which one color is becoming steadily more common
293 over time (e.g., $\sim 10\%$ of yellow pixels become blue pixels each second). Participants experienced
294 representational momentum for this change: When asked about the colors in the last frame of
295 the animation, they overestimated the prevalence of the color that was becoming more common.

296 Method

297 Experiment 6 followed the same procedure as Experiments 1 and 5 with a few modifications.
298 Instead of seeing a single square that changed in brightness or saturation, participants saw a

299 40x40 grid of pixels in which 75–100% of the pixels were one hue (the “original hue”) and the
300 remaining pixels were another hue (the “new hue”). Then, on each frame of the animation,
301 5 pixels would switch from being the original hue to being the new hue (with no change in
302 brightness or saturation). The pixels that switched were selected at random, so there was no
303 coherent motion within the image (i.e., the new hue was not spreading left-to-right or outward
304 from the middle of the frame).

305 Each pixel had a random brightness and saturation value (that stayed fixed over the course
306 of the animation). The original hue was chosen at random for each participant and stayed the
307 same from trial to trial. The new hue was always 180 degrees away from the original hue in
308 CIELCh color space. Animations were presented at 30 frames per second and were 8 seconds in
309 length. Animations were obscured by a mask after 1.5 to 6.5 seconds.

310 200 participants completed Experiment 6 (102 male, 98 female; mean age 38). 4 participants
311 were excluded according to our preregistered exclusion criteria. Another 2 participants were
312 excluded because they enrolled using the same Prolific account ID number as one another.

313 Our statistical analyses were identical to those used for Experiment 1 with two exceptions.
314 First, we increased the standard deviation and the bounds of the prior distributions (to 20
315 and $[-120, 120]$, respectively) to reflect the greater length of the animation. Second, there was
316 no “direction” parameter (e.g., “brightening” vs. “darkening”) because every trial was both a
317 “decreasing” trial (with respect to the original hue) and an “increasing” trial (with respect to the
318 new hue).

319 Results

320 Participants experienced representational momentum for the changing proportion: When asked
321 to select the final frame that they remembered seeing in the animation, they selected a frame
322 that was 4.77 frames further into the future on average (95% HDI of $[2.60, 6.93]$). In other
323 words, they remembered seeing about 1.5% more of the hue that was increasing in prevalence
324 (and 1.5% less of the hue that was decreasing in prevalence) than they really did. They did this
325 consistently, regardless of the hues involved: We split our data into 12 bins based on the starting

326 hue angle, with each bin covering 30 degrees (e.g., hue angle 0-30 degrees, 30-60 degrees, etc.)
327 and responses were future-biased in 11 out of 12 bins.

328 **Experiment 7: The Representation of Hue and the Limits** 329 **of Automatic Prediction**

330 Experiments 1–6 show that there are at least three cases where people appear to experience
331 representational momentum for a dimension of change that involves no motion whatsoever:
332 changes in brightness (Experiments 1–4), changes in color saturation (Experiment 5), and
333 changes in proportion (Experiment 6).

334 Experiment 7 tested whether people experience representational momentum for changes in
335 hue. However, unlike changing brightness, saturation, or proportion, we hypothesize that the
336 mind does not automatically represent the trajectory of changing hue. Brightness and saturation
337 are magnitudes and the trajectory of a monotonic change in either—or in a proportion, as in our
338 Experiment 6—is exceedingly obvious to an observer. By comparison, hue is not a magnitude
339 and—even though there is latent organization to hue representation that is captured by color
340 appearance models (e.g., orange is judged more similar to red than to blue; Fairchild, 2013)—our
341 minds may not automatically compute and explicitly represent the trajectory of hue change
342 through this latent space. As such, our (preregistered) hypothesis was that people would not have
343 strong automatic predictions about changes in hue, and, therefore, not exhibit representational
344 momentum for changing hue.

345 Experiment 7 also served as a powerful control. It used the exact same procedure as
346 Experiments 1 and 5, except that the stimulus changed in hue, rather than brightness or
347 saturation. Accordingly, a negative result would verify that our approach does not merely yield
348 future-biased responses in all cases and that the momentum effects that we observe are induced
349 by particular stimuli, rather than some artifact of our experimental procedure.

Method

Experiment 7 exactly replicated Experiment 1 except that the stimuli changed hue instead of becoming brighter or darker. The animation consisted of 180 frames equally spaced in CIELCh space between hue angles of 10 and 330 (again displayed at 30 frames per second). Lightness was held constant at 70 and chroma held constant at 36. The random noise mask on each trial featured the full range of hues. The direction of hue change (red-to-purple vs. purple-to-red) was randomly varied between participants (each direction equally likely).

200 participants completed Experiment 7 (94 male, 102 female, 4 non-binary; mean age 38): 7 participants who were excluded according to our preregistered exclusion criteria, 93 participants who saw red-to-purple animations, and 100 participants who saw purple-to-red animations.

Results

As we predicted, participants did not experience representational momentum for changing hue: On average, the last frame they reported seeing was 1.5 frames before the final frame displayed (95% HDI: [-2.12, -0.99] overall, [-3.07, -1.43] for red-to-purple, [-1.62, -0.05] for purple-to-red). Our preregistered standard for “no effect” was a 95% HDI entirely within the range [-2.5, 2.5], as we find here.

Discussion

Representational momentum transcends motion. Our minds are continually trying to predict the trajectory of our experiences and these predictions can distort our memories whether or not they are about literal, physical motion. Here, we provide clear demonstrations that people experience representational momentum for three different kinds of changes that involve no physical motion whatsoever: changes in brightness (Experiments 1 through 4), color saturation (Experiment 5), and proportion (Experiment 6). People misremember brightening stimuli as having brightened more than they really did and make analogous errors for darkening, saturating, and desaturating stimuli, as well as changes in relative proportion. Our findings also directly

375 challenge the longstanding claim that changes in brightness do not produce representational
376 momentum (using large, preregistered experiments with richer, more naturalistic stimuli).

377 We show that representational momentum is more than merely a motion-specific phenomenon,
378 but its true breadth remains unknown. Does it extend to changes in higher level visual features,
379 other perceptual modalities, or beyond perception? A fundamental challenge in future research
380 exploring these questions will be establishing that novel representational momentum effects
381 are not merely disguised representational momentum for motion. As we noted previously, the
382 state changes that have previously been shown to elicit representational momentum involve
383 motion (e.g., a shrinking ice cube), and prior demonstrations of representational momentum for
384 changing pitch have been challenged on the ground that this occurs only because changes in
385 pitch sound like objects in motion (Brehaut and Tipper, 1996). Gradual changes that do not
386 involve actual, apparent, or implied motion are surprisingly rare. However, as we have shown
387 here, this challenge is not insurmountable. Much opportunity for exploration remains. Do people
388 experience representational momentum for changes in intensity of odor? What about changes in
389 higher level properties such as symmetry or numerosity?⁶ Do people experience representational
390 momentum for conceptual changes (i.e., Constantinescu et al., 2016)? Additionally, future
391 work could investigate the domain-generalty of the mechanisms underlying different types of
392 representational momentum. We hypothesize that the underlying computational mechanism is
393 the same—the automatic prediction of continuous change through a representational space—but
394 we do not speculate about, e.g., the underlying neural mechanisms.

395 Past experiments have failed to find representational momentum for brightness (e.g., Brehaut
396 and Tipper, 1996; Favretto, 2002). Why did ours succeed? One possibility is that past studies
397 adapted the methods of the earliest experiments that demonstrated representational momentum

⁶In a phenomenon called operational momentum, people exhibit a momentum-like effect when estimating operations like arithmetic (e.g., overestimating sums and underestimating subtractions McCrink et al., 2007), but this is not the same as representational momentum for numerosity, i.e. *perceived* number. Although it hints at the possibility that spatial metaphor and spatial representations underwrite numerous cognitive capacities, including prediction (Constantinescu et al., 2016; Hubbard, 2014, 2015; Pinker, 2007), the existence of operational momentum does not already establish that representational momentum transcends motion; operational momentum occurs for mental operations, not extrapolating the trajectory of perceived changes. Meanwhile, our demonstration of representational momentum for proportion is not itself a demonstration of momentum for numerosity because participants could have been relying on the total area of the stimuli of the relevant color, rather than the number.

398 for motion, which meant using relatively impoverished stimuli to cue the trajectory of change
399 (e.g., three-frame animations). These were adequate to induce representational momentum for
400 moving objects, but may simply have been insufficient to induce momentum effects for changing
401 brightness. Our experiments used longer, smoother stimuli that may have been more effective in
402 eliciting momentum effects by providing a clearer signal of the trajectory of change to serve as a
403 basis for prediction.

404 In our final experiment, we probe the limits of automatic prediction. We show that, under
405 identical conditions, people experience no discernible representational momentum for changes in
406 hue (Experiment 7). Although these results alone cannot determine why this is the case, our
407 hypothesis is that the mind does not automatically compute and explicitly represent the trajectory
408 of hue change through latent color space in the way that it might do naturally for brightness,
409 saturation, and proportion within their respective representational spaces. There is a salient—but
410 ultimately unsuitable—alternative explanation for the pattern of effects that we observe: Changes
411 in brightness and saturation are changes in prothetic dimensions (i.e., the amount of something
412 is changing; Stevens, 1957; Stevens and Galanter, 1957) whereas changes in hue are changes in
413 a metathetic dimension (i.e., in a qualitative feature), so perhaps representational momentum
414 occurs for changes in prothetic dimensions, but not metathetic dimensions. However, this is
415 almost certainly not the case. Orientation and pitch are paradigmatic metathetic dimensions,
416 yet both exhibit representational momentum (Freyd and Finke, 1984; Kelly and Freyd, 1987).
417 Instead, we hypothesize that the occurrence of representational momentum depends on whether
418 the mind automatically and accurately predicts the trajectory of changes in a given dimension.
419 For prothetic dimensions, these predictions are particularly easy; they are increases and decreases
420 in a single magnitude. For metathetic dimensions, predictability may vary. For a rotating shape or
421 changing pitch the trajectory of change is obvious (e.g., clockwise or counterclockwise, increasing
422 or decreasing). By contrast, even though there is latent organization to hue representation, our
423 minds may not automatically compute and explicitly represent the trajectory of hue change
424 through this latent space. An interesting direction for future research would be to further test
425 this hypothesis by providing people with extensive experience with continuous hue change. If,

426 after this training, people begin to experience representational momentum for changing hue,
427 this would be strong evidence that the absence of momentum for hue change in the rest of us
428 directly follows from the fact that we cannot or do not automatically represent the trajectory of
429 changing hue. (And this would be a particularly persuasive result given that we might otherwise
430 expect expertise in an area to make us less likely to make memory errors in that area, rather
431 than more.)

432 Our final experiment also serves as an important control. Because we find no representational
433 momentum for changes in hue, we can rule out the possibility that our other findings are some
434 artifact of our experimental procedure that produces momentum-looking effects for any changing
435 stimuli: Our procedure reveals representational momentum in certain cases (e.g., changing
436 brightness, saturation, or proportion) without seeing it everywhere. For example, this makes it
437 unlikely that our results are driven by repulsive biases due to adaptation (e.g., Gibson, 1937;
438 Pascucci and Plomp, 2021). One might think that participants actually *experience* a 68%
439 brightness square as 70% brightness when it follows a 67% square because the visual system is
440 exaggerating the difference between the two (rather than misremembering what they saw due to
441 momentum). However, these kinds of repulsive biases are known to occur for changes in hue
442 (Gibson, 1937). Thus, given that our procedure finds no momentum-looking effects for changes in
443 hue, we think it is extremely unlikely that repulsive biases are driving the effects that we do see.⁷

444 Although our results in our final experiment met our preregistered standard for “no effect”,
445 participants did exhibit a trace amount of “negative momentum” for changing hue (about 1.5
446 frames worth), rather than showing no bias whatsoever. We cannot say why participants’
447 responses leaned slightly negative. One tempting explanation is that backward masking is
448 preventing people from seeing the final 1–2 frames of the stimulus that are on the screen before
449 the onset of the mask (e.g., Raab, 1963). In this case, the final frame that participants would
450 recall seeing would be 1–2 frames before the final frame that was presented. However, we
451 exactly replicated Experiment 7 while omitting the post-stimulus mask and obtained nearly

⁷A second reason that we do not think that adaptation effects in particular can account for our results is that Brehaut and Tipper (1996) did not see momentum-looking effects for changing brightness. The design of their experiments (e.g., stimulus timings) would have made them likely induce repulsion effects, yet they did not find any.

452 identical results (see Supplementary Materials), casting doubt on this as a possible explanation.
453 Understanding the cause of this slight negative momentum effect for changing hue will require
454 future research.

455 Our minds automatically predict the trajectory of objects through physical space. More
456 generally, however, we show here that they predict the trajectory of other varieties of change
457 within their respective representational spaces. These predictions distort our memories, and the
458 presence or absence of these distortions offer a window into the inner workings of perception,
459 memory and cognition. Finding representational momentum for a given variety of change
460 (such as brightness, color saturation, or proportion) strongly suggests that the mind represents
461 trajectory through the corresponding representational space, and that it uses this representation
462 of trajectory to engage in prediction. By contrast, the absence of representational momentum
463 (as in the case of hue) suggests that the mind only represents current and past position within
464 the corresponding representational space, and does not automatically compute and represent the
465 trajectory of changes through that space.

466 Navigating the world requires that our minds represent how things are and how they are
467 about to be. But, as is so often the case, systematic errors in these processes can reveal a great
468 deal about how the mind works.

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Supplementary Material for *Representational Momentum Transcends Motion*

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Supplementary Methods

General Methods (All Experiments)

All experiment scripts, data, and analysis scripts are available on OSF: <https://osf.io/j9d4a/>. Demos of all experiments are available here: <https://subjectivitylab.org/rm/>. All of our experiments were preregistered. Links to all preregistrations are in the OSF repository README.

Participants were adults in the United States recruited through the online platform Prolific and participated for pay. Participants could complete the experiment only if they were using Google Chrome and a display with a refresh rate of at least 30 Hz.

Experiment 1: Brightness (Basic Case)

Additional Implementation Details

CIELCh to RGB conversion was performed with chroma.js.

The mask image on each trial was one of seven different grayscale noise images, selected at random on each trial (each made from 122 by 122 pixels in which each pixel was randomly assigned a monochromatic RGB value of 0 to 255, then magnified to create a 490 by 490 pixel image).

On the first practice trial, there was no mask and participants could continue to see the final frame of the animation while making their response. They could not submit their response unless it was within 1 frame of the correct response. The remaining three practice trials were identical to the analyzed trials.

Additional Participant Details

Following our preregistered procedure, we recruited 200 participants, then recruited an additional batch of 20 participants because our original sample provided fewer than 90 participants in one of our two between-subjects conditions after applying our exclusion criteria (see Statistical Analyses in the paper).

32 Additional Statistical Analyses Details

33 Precisely, we modeled participant errors with:

```
brm(  
  error ~ 0 + Intercept + direction + (0 + Intercept | participant),  
  prior = prior(normal(0, 15), class = b, lb = -90, ub = 90),  
  iter = 10000, seed = 2024  
)
```

34 in brms version 2.20.4 and using brms defaults where not otherwise specified. (The model
35 does not feature random slopes for the effect of direction because this was a between-subjects
36 manipulation.) We used 4 Markov chains and 10,000 iterations per chain, including warmup.
37 (The `0 + Intercept` syntax is required to correctly set a prior on the intercept if predictors
38 have not all been mean-centered.)

39 Experiments 2–4: Replications with Different Tasks and Stimuli

40 Additional Implementation Details

41 In Experiment 3, the squares were 240 by 240 pixels, as in Experiments 1 and 2, but did not
42 have the 1 pixel black border used in Experiments 1 and 2.

43 Additional Participant Details

44 For both Experiment 2 and Experiment 4 (in accordance with preregistered procedure), we
45 recruited 100 participants, then recruited an additional batch of 10 participants because our
46 original sample provided fewer than 40 participants in one of our two between-subjects conditions
47 after applying our exclusion criteria. In Experiment 3, our original sample of 100 participants
48 yielded enough participants in each condition.

49 Additional Statistical Analyses Details

50 In Experiment 3, there were divergent transitions fitting the model using the default value
51 for `adapt_delta` (the step size during Hamiltonian Monte Carlo). In later experiments, we
52 preregistered that we would use a value of 0.9 for `adapt_delta` if this happened, but did not do
53 so for this experiment. We report the values from the model that we preregistered (which had
54 divergent transitions), but if the model is refit with `adapt_delta = 0.9`, there are no divergent
55 transitions and the results are extremely similar (no 95% HDI boundary shifts more than 0.05),
56 indicating that the divergent transitions did not affect the results.

57 Experiment 5: Representational Momentum for Saturation

58 Additional Implementation Details

59 As in all previous experiments, the squares were 240 by 240 pixels. As with the chromatic stimuli
60 in Experiment 3, there was no black border on the squares and the random noise mask on each
61 trial was matched to the hue of the stimulus on that trial.

62 The animations consisted of 90 frames equally spaced in CIELCh space between chroma
63 values of 0 and 75. The red stimulus had fixed lightness of 55 and hue of 30. The green stimulus
64 had fixed lightness of 75 and hue of 135. The blue stimulus had fixed lightness of 45 and hue
65 of 290. These values (and the change to 15 fps from 30 fps) ensured that every frame of each
66 animation used a distinct RGB value that could be displayed on a standard display (i.e., no
67 two frames were the same and the value of each RGB color channels was always between 0 and
68 255). As in all previous experiments, the squares were 240 by 240 pixels. As with the chromatic
69 stimuli in Experiment 3, there was no black border on the squares and the random noise mask
70 on each trial was matched to the hue of the stimulus on that trial. All other parameters were
71 the same as Experiment 1.

72 Additional Participant Details

73 100 participants completed Experiment 5 (45 male, 53 female, 2 non-binary; mean age 37). Our
74 final analyses included 53 participants from the saturating condition, 43 from the desaturating
75 condition, and excluded 4 participants according to our preregistered exclusion criteria.

76 Additional Statistical Analyses Details

77 Our methods for analyzing the data in Experiment 5 were identical to those for Experiment 3:
78 Chromatic Stimuli (i.e., identical to Experiment 1 except that we also modeled stimulus color).
79 The “direction” parameter of the model referred to the direction of change in saturation, rather
80 than brightness. Our preregistered prediction was again positive overall error (i.e., a 95% HDI
81 entirely above 0). We also computed 95% HDIs for error in both the saturating and desaturating
82 conditions, as well as within each of the three color conditions.

83 Experiment 6: Representational Momentum for Proportion

84 Additional Implementation Details

85 The stimulus arrays were 40 by 40, spanning 320 by 320 pixels (i.e., each large pixel in the array
86 was 8 by 8 pixels). Every large pixel in the array had fixed CIELCh chroma of 34 and a randomly
87 selected brightness value between 60% and 70%. The values were held constant over the course
88 of each trial; only hue could change (from the original hue to the new hue). The masks were 320
89 by 320 squares with smooth color gradients of the original hue fading into the new hue with a
90 chroma of 34 and a brightness of 65%, oriented at a random angle.

91 Experiment 7: The Representation of Hue and the Limits of Automatic 92 Prediction

93 There are no supplementary methods for Experiment 7. Everything is covered in the main text.

94 Rare Bug

95 Due to a bug in our code, participants could inadvertently trigger unintended behavior (e.g.,
96 skipping a trial without providing a response) under exceedingly rare circumstances in all
97 experiments except Experiments 4 and 6. We repeated all of the analyses reported in the main

98 text after excluding data from all participants who triggered the bug at any point (fewer than
99 2% of our participants). There were no qualitative differences in any of our preregistered or post
100 hoc analyses and only miniscule quantitative differences. For details on the bug and the code
101 used for the reanalyses, see the OSF repository linked above.

102 **Supplementary Results**

103 Here we report some additional analyses that do not bear on our hypotheses (e.g., comparisons
104 between conditions like brightening vs. darkening), as well as standardized versions of our central
105 analyses. All intervals are 95% HDIs.

106 **Experiment 1: Brightness (Basic Case)**

107 For all experiments except Experiment 4, we computed standardized effect sizes (Cohen’s d)
108 by dividing the values of the posterior draws by the pooled standard deviation of the outcome
109 variable (frames of error) and then computing 95% HDIs based on those draws.

110 In Experiment 1, the posterior for the standardized overall effect size was $d = [0.24, 0.35]$
111 ($d = [0.40, 0.55]$ for brightening and $d = [0.03, 0.20]$ for darkening). The standardized effect size
112 for the difference between brightening and darkening conditions was $d = [0.24, 0.47]$.

113 **Experiment 2: Reversed Slider**

114 The posterior for the standardized overall effect size was $d = [0.41, 0.57]$ ($d = [0.53, 0.73]$ for
115 brightening and $d = [0.24, 0.48]$ for darkening). The standardized effect size for the difference
116 between brightening and darkening conditions was $d = [0.11, 0.42]$.

117 **Experiment 3: Chromatic Stimuli**

118 The posterior for the standardized overall effect size was $d = [0.26, 0.39]$ ($d = [0.30, 0.48]$ for
119 brightening and $d = [0.17, 0.35]$ for darkening; red: $d = [0.19, 0.34]$, blue: $d = [0.31, 0.48]$,
120 green: $d = [0.24, 0.41]$). The standardized effect size for the difference between brightening and
121 darkening conditions was $d = [0.00, 0.26]$.

122 **Experiment 4: Two Alternatives**

123 For Experiment 4 (in which our central analysis was a logistic regression), we converted log-odds
124 coefficients to Cohen’s d using the standard conversion factor, $\pi/\sqrt{3}$. The posterior for the
125 standardized overall effect size was $d = [0.18, 0.29]$ ($d = [0.01, 0.11]$ for the effect of brightening
126 vs. darkening).

127 **Experiment 5: Saturation**

128 The posterior for the standardized overall effect size was $d = [0.21, 0.36]$ ($d = [0.26, 0.47]$ for
129 saturating and $d = [0.08, 0.30]$ for desaturating; red: $d = [0.27, 0.46]$, blue: $d = [0.19, 0.38]$,
130 green: $d = [0.10, 0.28]$). The standardized effect size for the difference between saturating and
131 desaturating conditions was $d = [0.01, 0.33]$.

Experiment 6: Proportion

The posterior for the standardized overall effect size was $d = [0.07, 0.19]$.

Experiment 7: Hue

The posterior for the standardized overall effect size was $d = [-0.18, -0.08]$. The posterior for the standardized effect of direction (i.e., the difference between the increasing and decreasing hue angle conditions) was $d = [-0.22, -0.03]$.

Supplementary Experiment: Omitted Mask

Methods

In a supplementary experiment, we exactly replicated Experiment 7, except that participants saw a blank screen for 1 second after the stimulus disappeared, instead of seeing a colorful noise image for 1 second. All other methods were identical to Experiment 7.

220 participants completed Experiment 7 (121 male, 98 female, 1 non-binary; mean age 44): 8 participants who were excluded according to our preregistered exclusion criteria, 116 participants who saw red-to-purple animations, and 96 participants who saw purple-to-red animations.

Results

The final frame that participants reported seeing was 1.7 frames before the final frame displayed (similar to Experiment 7, where it was 1.5 frames; 95% HDI: $[-2.07, -1.05]$ overall, $[-3.40, -2.04]$ for red-to-purple, $[-1.13, 0.37]$ for purple-to-red).

The posterior for the standardized overall effect size was $d = [-0.16, -0.08]$. The standardized effect for difference between the increasing and decreasing hue angle conditions was $d = [-0.27, -0.11]$.